

# POSTER PRESENTATION SCHEDULE 2025

## Poster Session #1 - January 15th 14:30 - 15:30

\*Best Poster Award Contestant

### Artificial Intelligence/Machine Learning

VENUE	ID	AUTHOR	POSTER TITLE
Trozelligalleriet	TS1B24	Sofia Andersson	Two-state protein design using deep learning
Trozelligalleriet	TS1B26	Linus Aronsson	Correlation Clustering with Active Learning of Pairwise Similarities
Trozelligalleriet	TS1B28	Ahmet Balcioglu	Identifiable latent bandits: Combining observational data and exploration for personalized healthcare
Trozelligalleriet	TS1B30	Josef Bengtson	Geometric Consistency for View Conditioned DiffusionModels
Trozelligalleriet	TS1B32	David Björkstrand	Optical Human 3D Motion Capture in Professional Football
Trozelligalleriet	TS1B34	Francisco Calatrava Nicolás	Sensor-Based Human Activity Recognition
Trozelligalleriet	TS1B36	Amandine Caut	Wordalisation
Trozelligalleriet	TS1C25	Télio Cropsal	Diffusion models for predicting cell morphology
Trozelligalleriet	TS1C27	Ludvig Dillén	Asymmetric Image Matching
Trozelligalleriet	TS1C29	Dominik Drexler	Symmetries and Expressive Requirements for Learning General Policies
Trozelligalleriet	TS1C31	Mehrdad Farahani	Deciphering the Interplay of Parametric and Non-parametric Memory in Retrieval-augmented Language Models
Trozelligalleriet	TS1C33	Markus Fritzsche	How to Train Neural Networks for Classical Planning
Trozelligalleriet	TS1C35	Sonakshi Garg	Privacy Preservation of High-dimensional Data using Manifold Learning
Trozelligalleriet	TS1D1	Amaury Gouverneur	An Information-Theoretic Analysis of Thompson Sampling for Logistic Bandits
Trozelligalleriet	TS1D3	Emma Granqvist	Multi-Step Retrosynthesis Prediction Using a Decision Transformer
Trozelligalleriet	TS1D5	Jingyu Guo	Random Token Fusion for Multi-View Medical Diagnosis
Trozelligalleriet	TS1D7	Eduardo Gutierrez Maestro	Unlocking the Challenges in Emotion Recognition Systems through Artificial Intelligence
Trozelligalleriet	TS1D9	Olle Hansson	Joint CPU-FPGA Hardware-Aware Quantized Training of Graph Convolutional Networks

Trozelligalleriet	TS1D11	Yikun Hou	Implicit Regularization in Matrix Factorization and Neural Networks with Diagonal Layers
Trozelligalleriet	TS1D13	Paul Háusner	Learning incomplete factorization preconditioner for GMRES
Trozelligalleriet	TS1D15	Yifei Jin	Heuristic-Informed Neural Surrogate on Wireless Network Representations
Trozelligalleriet	TS1E1	Marcus Lassila	Membership Inference Attacks on Graph Neural Networks
Trozelligalleriet	TS1E3	Kristina Levina	Reinforcement Learning with Reward Machines for Energy Optimisation
Trozelligalleriet	TS1E5	Maja Lindström	Compressing regularised dynamics improves link prediction in sparse networks
Trozelligalleriet	TS1F2	Julian Alfredo Mendez	A Model-driven and Formal Approach to Operationalizing Notions of Fairness
Trozelligalleriet	TS1F4	Hadi Mousanejad Jeddi	Confidence Calibration in Quantized Graph Neural Networks Using Temperature Scaling
Trozelligalleriet	TS1F6	Newton Mwai	Batched fixed-confidence pure exploration for bandits with switching constraints
Trozelligalleriet	TS1F8	Adam Drucu	Neural Architecture Search for Telecoms
Flygeln	FS1J1	Joana Palés Huix	Are Natural Domain Foundation Models Useful For Medical Image Classification?
Flygeln	FS1J3	Sanna Persson	Generating virtual Magnetic Resonance Elastography
Flygeln	FS1J5	Emanuel Sanchez Aimar	Flexible Distribution Alignment: Towards Long-tailed Semi-supervised Learning with Proper Calibration
Flygeln	FS1J7	Wei Shi	Improving the Energy Performance of Battery-Powered Mobile Networks via Reinforcement Learning
Flygeln	FS1K1	Stefan Stojanovic	Reinforcement Learning with Low-rank Structure?
Flygeln	FS1K3	Minerva Suvanto	Part-of-speech taggers' performance reduces on novel data sets
Flygeln	FS1K5	Magnus Tarle	Reinforcement Learning for Electrical Power System Control
Flygeln	FS1K7	John Törnblom	Formal Reasoning about Input-Output Relations of Tree Ensembles
Flygeln	FS1L1	Matthias Wagner	AI Act High-Risk Requirements Readiness: Industrial Perspectives and Case Company Insights
Flygeln	FS1L3	Erik Wallin	ProHOC: Probabilistic Hierarchical Out-of-Distribution Classification via Multi-Depth Networks
Flygeln	FS1L5	Zesen Wang	Efficient Decentralized Training of DNNs
Flygeln	FS1L7	Karol Wojtulewicz	Video Models for Sports Analytics
Flygeln	FS1M1	Yushan Zhang	Fault Tolerance for Mission-Critical Edge Applications
Flygeln	FS1M3	Hampus Åström	Autonomous Learning with Goals
Flygeln	FS1M5	Valency Colaco	Fast Evasion Detection & Alert Management in Tree-Ensemble-Based Intrusion Detection Systems
Flygeln	FS1M7	Jingru Fu	Unsupervised Domain Adaptation for Pediatric Brain Tumor Segmentation
Flygeln	FS1N1	Filip Kronström	*Predicting yeast properties from knowledge graphs using GNNs and box embeddings
Flygeln	FS1N3	Niloofar Momeni	Parkinson's Detection Using Voices on Mobile Devices

Flygeln	FS1N5	Franco Ruggeri	Explainable Reinforcement Learning via Temporal Policy Decomposition
Flygeln	FS1N7	Ziliang Xiong	Uncertainty Quantification Metrics for Deep Regression
Flygeln	FS1N9	Qingwen Zhang	Self-Supervised Understanding of Dynamic Scenes - Let Data Be the Teacher

## Artificial Intelligence/Math

VENUE	ID	AUTHOR	POSTER TITLE
Trozelligalleriet	TS1A2	Emma Andersdotter	Exploring the Universality of Manifold Neural ODEs
Trozelligalleriet	TS1A4	Noel Arteche	Quantum Computers Cannot Automate Theorem Proving (Unless Post-Quantum Cryptography Breaks)
Trozelligalleriet	TS1A6	Isac Boström	Posterior Sampling of Word Embeddings
Trozelligalleriet	TS1A8	Kasper Bågmark	Strong convergence for a classical prediction-update scheme under a parabolic Hörmander condition based on the Fokker-Planck equation
Trozelligalleriet	TS1A10	Danai Deligeorgaki	Unconditional Equivalence in Causal Discovery
Trozelligalleriet	TS1A12	Adrian Edin	Temporal Predictive Coding for Gradient Compression in Distributed Learning
Trozelligalleriet	TS1A14	Lukas Evehorn	Solving the Vehicle Routing Problem for Heavy-Duty Electric Vehicles with Optimality Guarantees
Trozelligalleriet	TS1A16	Paul Höft	Graph-based Orders for Saturated Cost Partitioning
Trozelligalleriet	TS1A18	Erik Karlsson Nordling	Searching for the unknown dynamics in continuous partially observable MDPs
Trozelligalleriet	TS1A20	Thibault Marette	Visualizing Overlapping Biclusterings and Boolean Matrix Factorizations
Trozelligalleriet	TS1A22	Philipp Misof	Equivariant Neural Tangent Kernels
Trozelligalleriet	TS1A24	Mathias Müller	Recursive Learning of Asymptotic Variational Objectives
Trozelligalleriet	TS1B17	Max Nilsson	Algorithm Design with Steering Vectors
Trozelligalleriet	TS1C16	Elias Nyholm	Nonlinear Equivariant Neural Networks on Homogeneous Spaces
Trozelligalleriet	TS1C18	Oskar Nordenfors	Ensembles Learn Equivariance Through Data Augmentation
Flygeln	FS1O2	Mika Skjelnes	Cost Saturation for Multiple Sequence Alignment
Flygeln	FS1O4	Selma Tabakovic	Sepsis Treatment via Personalized Reinforcement Learning: A Multi-Head Dueling Double Deep Q-Network Approach
Flygeln	FS1P2	Ying Wang	A Study of Regret Minimization for Static Scalar Nonlinear Systems
Flygeln	FS1P4	Anton Åkerman	A characterization of nonexpansive frugal splitting methods
Flygeln	FS1Q2	Andy Oertel	*End-to-End Verification for Subgraph Solving End-to-End Verification for Subgraph
Flygeln	FS1Q4	Joannes Vermant	*Rigidity and flexibility using graphs of groups

## Autonomous Systems

VENUE	ID	AUTHOR	POSTER TITLE
Trozelligalleriet	TS1B2	Martin Andersson	Uplink Symbol Detection in Dynamic TDD MIMO Systems with AP-AP Interference
Trozelligalleriet	TS1B4	Erik Brorsson	Safe and Efficient Collaborative Automation Systems
Trozelligalleriet	TS1B6	Erik Börve	Interactive Motion Planning with Learning-based Optimal Control
Trozelligalleriet	TS1B8	Paula Carbó Cubero	LaTTE: Self-supervised Latent Feature Maps for Heterogeneous Pose Estimation
Trozelligalleriet	TS1B10	David Dörner	Distributed Control of Underwater Robots
Trozelligalleriet	TS1B12	Gianfilippo Fornaro	Safety and performance of cooperative automated vehicles
Trozelligalleriet	TS1B14	Han Fu	Auto-repair without test cases: How LLMs fix compilation errors in large industrial embedded systems
Trozelligalleriet	TS1G1	Victor Pettersson	Vehicular Antenna Deployments for Downlink Positioning
Trozelligalleriet	TS1G3	Farhan Rasheed Ahmed	Topological Data Analysis for Spatial Data
Trozelligalleriet	TS1G5	Marko Guberina	Hand-arm coordination control for robot interaction tasks
Trozelligalleriet	TS1G7	Maciej Wozniak	Self-Supervised Learning for Autonomous Driving
Trozelligalleriet	TS1C1	Jonas Hansson	Transient Analysis and Control for Scalable Network Systems
Trozelligalleriet	TS1C3	Ayesha Jena	Support for critical collaboration tasks through gaze guidance and visual augmentation
Trozelligalleriet	TS1C5	Abhishek Kashyap	Exploiting Radiance Fields for Grasp Generation on Novel Synthetic Views
Trozelligalleriet	TS1C7	Elias Krantz	Distributed Control of Autonomous Space Vehicles
Trozelligalleriet	TS1C9	Adam Lilja	Online Mapping for Autonomous Driving
Trozelligalleriet	TS1C11	Talitha Nauta	Stealthy Delay Attacks for Cyber-Physical Systems
Trozelligalleriet	TS1C13	Deepthi Pathare	Micro-To-Macro Traffic Modelling with Machine Learning
Trozelligalleriet	TS1C15	Marco Spanghero	GNSS spoofing detection using carrier phase and consumer INS
Flygeln	FS1H2	Peter Stoltenberg	Intelligent Trajectory Predictions at Sea using Neural Ordinary Differential Equations
Flygeln	FS1H4	Gustaf Söderholm	Pace: Modelling time and timing in joint Human-AI collaboration
Flygeln	FS1H6	Joris Verhagen	Robustness Metrics for Motion Planning and Control with STL Specifications
Flygeln	FS1H8	Rebecka Winqvist	Planning under Uncertain Failure Severity
Flygeln	FS1I2	Gabriel Arslan Waltersson	*In-Hand Slip-Aware Object Manipulation
Flygeln	FS1I4	Ali Nouri	LLM-Based Multi-Agent System to Accelerate DevSafeOps for Autonomous Driving

Flygeln	FS116	Matti Vahs	Risk-aware Control of Robotic Systems via Control in Belief Space
Flygeln	FS118	Gustav Zetterqvist	*Directional Sensitivity-Based DOA Estimation Using a Fourier Series Model

## Software

VENUE	ID	AUTHOR	POSTER TITLE
Trozelligalleriet	TS1B20	Máté Földiák	Architecture Synthesis and Dependability Evaluation of System Models
Trozelligalleriet	TS1B22	Lo Heander	What Questions do Developers Ask During Code Review?
Trozelligalleriet	TS1C20	Mojtaba Moazen	TAPShield: Securing Trigger-Action Platforms against Strong Attackers
Trozelligalleriet	TS1C22	Harald Ng	Auto-Reliable Replicated Data Services
Flygeln	FS1R1	Nayereh (Tanaz) Rasouli	Fault Tolerance for Mission-Critical Edge Applications
Flygeln	FS1R3	André Silva	RepairLLaMA: Efficient Representations and Fine-Tuned Adapters for Program Repair
Flygeln	FS1S1	Gustaf Waldemarson	Succinct Opacity Micromaps
Flygeln	FS1S3	Antonia Welzel	Resolving Requirement Conflicts at Runtime

# POSTER PRESENTATION SCHEDULE 2025

## Poster Session #2 - January 15th 15:30 - 16:30

\*Best Poster Award Contestant

### Artificial Intelligence/Machine Learning

VENUE	ID	AUTHOR	POSTER TITLE
Trozelligalleriet	TS2B23	Amirhossein Ahmadian	Improved Contrastive Predictive Coding for Time Series Out-Of-Distribution Detection with Human Activity Data
Trozelligalleriet	TS2B25	Victor Aregbede	Curiosity Based Affordance Learning
Trozelligalleriet	TS2B27	Ioannis Atahansiadis	Prior Learning in Introspective VAEs
Trozelligalleriet	TS2B29	Ermanno Bartoli	Planning Around Humans with 3DSSG
Trozelligalleriet	TS2B31	Axel Berg	Towards Federated Learning with on-device Training and Communication in 8-bit Floating Point
Trozelligalleriet	TS2B33	Daniel Brunnsåker	Automated Generative Experimental Design via Relational Learning-Guided Large Language Models
Trozelligalleriet	TS2B35	Gabriele Calzolari	Multi-Agent Coordination in Robotic Missions
Trozelligalleriet	TS2C24	Filip Cornell	Unsupervised Ontology- and Taxonomy Construction through Hyperbolic Relational Domains and Ranges
Trozelligalleriet	TS2C26	Leo Dahl	Multi-molecular phenotyping in a self-sampling population
Trozelligalleriet	TS2C28	Yifan Ding	Do Diffusion Models Know What They Don't Know in Representation Space?
Trozelligalleriet	TS2C30	Xavante Erickson	System 1 – System 2
Trozelligalleriet	TS2C32	Dominik Fay	Federated Learning for Smart Radiotherapy Systems
Trozelligalleriet	TS2C34	Martin Funkquist	Acting on Language Instructions
Trozelligalleriet	TS2C36	Ciwan Ceylan	Scalable Unsupervised Feature Selection with Reconstruction Error Guarantees via QMR Decomposition
Trozelligalleriet	TS2D2	Hariprasath Govindarajan	On partial prototype collapse in the DINO family of self-supervised learning methods
Trozelligalleriet	TS2D4	Hampus Gummesson Svensson	Diversity-Aware Reinforcement Learning for de novo Drug Design
Trozelligalleriet	TS2D6	Sargam Gupta	Haha! Caught you: Evaluating StyleID, a tool for anonymizing facial images using Record Linkage Attacks
Trozelligalleriet	TS2D8	Lovisa Hagström	From parametric memory to retrieved contexts. Studies of language models (LMs) and factual knowledge.

Trozelligalleriet	TS2D10	Sonia-Florina Horchidan	Toward Building Reliable Hybrid Neural Graph Databases
Trozelligalleriet	TS2D12	Johannes Hågerlind	Temporally-consistent 3D Reconstruction of Seabirds
Trozelligalleriet	TS2D14	Shutong Jin	PACA: Perspective-Aware Cross-Attention Representation for Zero-shot Scene Rearrangement
Trozelligalleriet	TS2D16	Håkan Karlsson Faronius	Independence is not the issue: Exploring common assumptions in Neurosymbolic AI
Trozelligalleriet	TS2E2	Cuong Le	Integrating Physics-based Knowledge into Vision-based 3D Human Motion Capture
Trozelligalleriet	TS2E4	Carl Lindström	Neural Rendering for Autonomous Driving
Trozelligalleriet	TS2F1	Alejandro Luque Cerpa	Syntax-Guided Program Synthesis for Class Activation Mapping
Trozelligalleriet	TS2F3	Olivier Moliner	Sparse Multiview Open-Vocabulary 3D Detection
Trozelligalleriet	TS2F5	Farid Musayev	Combining Policies and Heuristics for Classical Planning
Trozelligalleriet	TS2F7	Matthias Möller	Neurosymbolic Rule Induction
Trozelligalleriet	TS2F9	Joel Oskarsson	Probabilistic Weather Forecasting with Hierarchical Graph Neural Networks
Flygeln	FS2j2	Leonard Papenmeier	TBD
Flygeln	FS2J4	Asma Raeisi	Cut-and-Paste Synthetic Data Generation for Instance Segmentation
Flygeln	FS2J6	Jack Sandberg	Bayesian Analysis Ofcombinatorial Gaussianprocess Bandits With Applications To Energy-Efficient Navigation
Flygeln	FS2J8	Signe Sidwall Thygesen	Data abstractions for visual analysis of electronic structures
Flygeln	FS2K2	Jonathan Styrud	Fault tolerant and long-term robot policies from natural language instructions
Flygeln	FS2K4	Alkis Sygkounas	REvolve: Reward Evolution with Large Language Models using Human Feedback
Flygeln	FS2K6	Adam Tonderski	Neural Simulation for Autonomous Driving
Flygeln	FS2K8	Juan Viguera Diez	Boltzmann priors for Implicit Transfer Operators (BoPITO)
Flygeln	FS2L2	James Waguespack	Monocular Human Motion Estimation
Flygeln	FS2L4	Nana Wang	Simultaneous Topology Identification and Control for Complex Networks
Flygeln	FS2L6	Alexander Gower	Phenotypes And Philosophy: Formalising Systems Biology Hypotheses for a Robot Scientist
Flygeln	FS2L8	Fereidoon Zangeneh	VAEs for Camera Relocalization
Flygeln	FS2M2	Xiaomeng Zhu	Computer Vision for Manufacturing Quality Inspection with Synthetic Data
Flygeln	FS2M4	Amr Alkhatib	*Prediction Via Shapley Value Regression
Flygeln	FS2M6	Johan Edstedt	*RoMa: Robust Dense Feature Matching
Flygeln	FS2M8	Ahmad Saeed Khan	On the Effects of Irrelevant Variables in Treatment Effect Estimation with Deep Disentanglement
Flygeln	FS2N2	Xixi Liu	TAG: Text Prompt Augmentation for Zero-Shot Out-of-Distribution Detection

Flygeln	FS2N4	Livia Qian	Backchannel modeling and prediction
Flygeln	FS2N6	Ahmet Ercan Tekden	*Data-Efficient Representation Learning for Grasping and Manipulation
Flygeln	FS2N8	Yi Yang	Challenges in Motion Prediction for Autonomous Driving

## Artificial Intelligence/Math

VENUE	ID	AUTHOR	POSTER TITLE
Trozelligalleriet	TS2A1	Jens Agerberg	Certifying Robustness via Topological Representations
Trozelligalleriet	TS2A3	Aban Ansari-Önneham	On finite termination of quasi-Newton methods on quadratic problems
Trozelligalleriet	TS2A5	Raghav Bongole	Information-Theoretic Bounds for Reinforcement Learning based on Duality
Trozelligalleriet	TS2A7	Adam Breitholtz	FedPALS: A method for mitigating label shift in federated learning
Trozelligalleriet	TS2A9	Oscar Carlsson	A new perspective and contextualisation of the group equivariant CNN
Trozelligalleriet	TS2A11	Michele Di Sabato	Clustering Misaligned Functional Data: An Application to Lake Sediments
Trozelligalleriet	TS2A13	Sólrún Einarsdóttir	Neuro-Symbolic Lemma Conjecturing
Trozelligalleriet	TS2A15	Yacoub Hendi	Learning Group Invariant Ricci-flat Metrics
Trozelligalleriet	TS2A17	Erik Jansson	Generating Non-Stationary Gaussian Processes on Curved Domains
Trozelligalleriet	TS2A19	Jacob Lindbäck	Parallel gradient computations via asynchronous splitting methods
Trozelligalleriet	TS2A21	Hoomaan Maskan	Revisiting Frank-Wolfe for Nonconvex Optimization
Trozelligalleriet	TS2A23	Vincent Molin	Transport Accelerated Simulated Annealing
Trozelligalleriet	TS2B16	Amanda Nilsson	expDSE: Accurate Initialization-Free Projective Factorization using Exponential Regularization
Trozelligalleriet	TS2B18	Viktor Nilsson	A variational approach to large deviations in Schrödinger bridges
Trozelligalleriet	TS2C17	Aurora Poggi	Data-Driven model for discovery of intracellular calcium oscillations behaviour
Flygeln	FS2O1	Shamisa Shoja	Complexity Certification of Branch-and-Bound Methods for MILP and MIQP
Flygeln	FS2O3	Karlo Palenzuela	Communication-Efficient Federated Learning with Multiple Local Steps
Flygeln	FS2P1	Damien Van Meerbeeck	Classical Planning using Constraint Programming and Belief Propagation
Flygeln	FS2P3	Björn Wehlin	Large-Scale Topological Data Analysis
Flygeln	FS2Q1	Jonas Conneryd	Graph Coloring Is Hard on Average for Polynomial Calculus
Flygeln	FS2Q3	Firooz Shahriari-Mehr	Asynchronous Decentralized Optimization with Constraints: Achievable Speeds of Convergence for Directed Graphs



## Autonomous Systems

VENUE	ID	AUTHOR	POSTER TITLE
Trozelligalleriet	TS2B1	Ahmed Al Bayati	Offloading of Time-Optimal Motion Planning with Jerk Constraints
Trozelligalleriet	TS2B3	Enno Breukelman	Confidentiality in Networked Control Systems
Trozelligalleriet	TS2B5	Marcel Büsching	Cloth-Splatting: 3D Cloth State Estimation from RGB Supervision
Trozelligalleriet	TS2B7	Rafael Ignacio Cabral Muchacho	Adaptive Distance Functions for Robotic Manipulation
Trozelligalleriet	TS2B9	Xiao Chen	Safe platoon and intersection coordination of connected and automated vehicles
Trozelligalleriet	TS2B11	Cihan Eryonucu	ARGUS: Preventing Sybils for Mobile Crowdsensing User Registration
Trozelligalleriet	TS2B13	Sebastiano Fregnan	Whole-Body Compliant Robotic Manipulation
Trozelligalleriet	TS2G2	Anja Hellander	Optimized Task and Motion Planning
Trozelligalleriet	TS2G4	Arvid Fåldin	Synthesizing multi-log grasp poses
Trozelligalleriet	TS2G6	Magnus Gyllenhammar	A Methodology for Runtime Assessment of the Quantitative Risk Norm for ADSs
Trozelligalleriet	TS2G8	Zheng Jia	Optimization-Based Path-Velocity Control for Time-Optimal Path Tracking under Uncertainties
Trozelligalleriet	TS2C2	Marco Iannotta	On the Fly Adaptation of Behavior Tree-Based Policies
Trozelligalleriet	TS2C4	Prabhat Kumar Jha	TBD
Trozelligalleriet	TS2C6	Hedieh Khosravi	Cluster-based dynamic channel characterization for mmWave communication and sensing
Trozelligalleriet	TS2C8	Malte Larsson	A Roomful of Distances
Trozelligalleriet	TS2C10	Hannes Marklund	Parameters can be identified under non-ideal constraints
Trozelligalleriet	TS2C12	Truls Nyberg	Share the Unseen
Trozelligalleriet	TS2C14	José Pedro	Going Beyond the Frontier in Autonomous Exploration
Flygeln	FS2H1	Yde Sinnema	How do timing misalignments affect real-time control systems?
Flygeln	FS2H3	Emil Sundström	Control Offloading for UAVs
Flygeln	FS2H5	Gustav Vallinder	Motion control for autonomous semi-trailer trucks on low-friction roads
Flygeln	FS2H7	Emil Wiman	Autonomous 3D Exploration in Large-Scale Environments with Dynamic Obstacles
Flygeln	FS2I1	Zhaozhan Yao	Convex polygonal formation of multi-vehicle systems
Flygeln	FS2I3	Adam Miksits	*Communication and Control Co-Design for Risk-Aware Safety of Mobile Robots with Offloaded Localization
Flygeln	FS2I5	Momina Rizwan	Enhancing robot autonomy: Introducing safety strategies for immediate recovery

Flygeln FS217 Bernhard Wullt Probabilistic Bubble RoadMap

## Software

VENUE	ID	AUTHOR	POSTER TITLE
Trozelligalleriet	TS2B19	Sabina Akbarova	Ready to Test Your (software's) Boundaries? FiTBVE Uncovers What Others Miss
Trozelligalleriet	TS2B21	Jens Gulin	Alternative implementations of the Auxiliary Duplicating Permutation Invariant Training
Trozelligalleriet	TS2C19	Malsha Mahawatta	Evaluating and Enhancing Trustworthiness of LLMs in Perception Tasks
Trozelligalleriet	TS2C21	Antonio Napoli	Enumeration Synthesis of Instruction Leakage Enhanced by Large-Language Models
Trozelligalleriet	TS2C23	Bruno Kreyszig	Analyzing Prerequisites of Java Insecure Deserialization
Flygeln	FS2R2	Javier Ron	Automated N-Version Programming with LLMs
Flygeln	FS2R4	Ahmad B. Usman	Update at Your Own Risk: Analysis and Recommendations for Update-Related Vulnerabilities
Flygeln	FS2S2	Yiran Wang	Static BugDetection for ML Programs
Flygeln	FS2S4	Johannes Wilson	Analysing TLS Implementations using Full-Message Symbolic Execution