Enhancing NeRF-based reconstruction of automotive scenes

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Summary

In this project, we have developed a novel view synthesis method specifically tailored for automotive data. We improve performance compared to current methods by modeling important characteristics for both cameras and lidars - including rolling shutter, beam divergence and ray dropping - as well as decreasing training times. We verify its performance on Zenseact Open Dataset (ZOD), achieving state-of-the-art performance for all performance metrics.

WARA connection

This project is **not connected to any WARA.**