# Constraint Satisfaction Problems

George Osipov

Linköping University

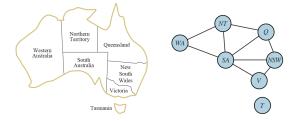
June 19, 2021

George Osipov Constraint Satisfaction Problems

Does this system of linear equations modulo 2 have a solution?

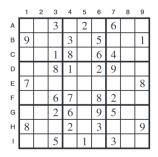
- $x_1 + x_2 + x_5 = 1 \mod 2$
- $x_1 + x_3 + x_4 = 1 \mod 2$
- $x_2 + x_3 + x_5 = 0 \mod 2$
- $x_2 + x_3 + x_4 = 1 \mod 2$

# Example 2: Coloring



Can we color all states of Australia with red, green, and blue so that no two neighboring states are assigned the same color?

# Example 3: Sudoku



Can we fill in the blanks with digits  $1, 2, \ldots, 9$  so that no digit appears twice in any row, column or  $3 \times 3$  box?

#### Constraint Satisfaction Problem (CSP)

- INSTANCE: (V, D, C), where
  - $\blacksquare$  V is the set of variables,
  - $\blacksquare$  D is the set of values,
  - $\blacksquare$  C is the set of constraints.

QUESTION: Is there an assignment of values to the variables that satisfies all constraints?

Does this system of linear equations modulo 2 have a solution?

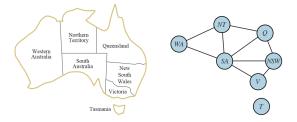
$$x_1 + x_2 + x_5 = 1 \mod 2$$
  

$$x_1 + x_3 + x_4 = 1 \mod 2$$
  

$$x_2 + x_3 + x_5 = 0 \mod 2$$
  

$$x_2 + x_3 + x_4 = 1 \mod 2$$

Variables:  $\{x_1, x_2, x_3, x_4, x_5\}$ . Values:  $\{0, 1\}$ . Constraints are  $x + y + z = 0 \mod 2$ ,  $x + y + z = 1 \mod 2$ . Can we color all states of Australia with red, green, and blue so that no two neighboring states are assigned the same color?

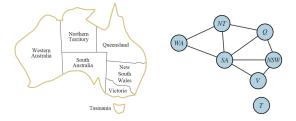


Variables:  $\{WA, NT, SA, NSW, V, SA, T\}$ .

Values:  $\{ red, green, blue \}$ .

Constraints:  $WA \neq NT$ ,  $WA \neq SA$ ,  $NT \neq SA$ , ...

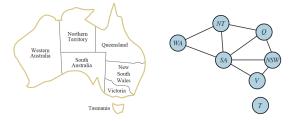
Can we color all states of Australia with red, green, and blue so that no two neighboring states are assigned the same color?



Variables:  $\{WA, NT, SA, NSW, V, SA, T\}$ . Values:  $\{red, green, blue\}$ .

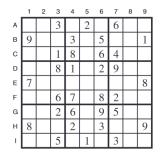
Constraints:  $WA \neq NT$ ,  $WA \neq SA$ ,  $NT \neq SA$ , ...

Can we color all states of Australia with red, green, and blue so that no two neighboring states are assigned the same color?



Variables:  $\{WA, NT, SA, NSW, V, SA, T\}$ . Values:  $\{\text{red}, \text{green}, \text{blue}\}$ . Constraints:  $WA \neq NT, WA \neq SA, NT \neq SA, \dots$ 

Can we fill in the blanks with digits  $1, 2, \ldots, 9$  so that no digit appears twice in any row, column or  $3 \times 3$  box?

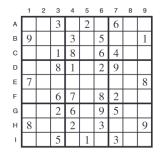


Variables: A1, A2,  $\ldots$ , I9 (81 in total).

Values: 1, 2, 3, 4, 5, 6, 7, 8, 9.

Constraints are of two types: (i) B1 = 9, ..., H9 = 9 and (ii) AllDiff(A1,...,A9), AllDiff(A1,...,I1), AllDiff(A1,...,C3), ...

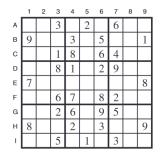
Can we fill in the blanks with digits  $1, 2, \ldots, 9$  so that no digit appears twice in any row, column or  $3 \times 3$  box?



Variables: A1, A2, ..., I9 (81 in total). Values: 1,2,3,4,5,6,7,8,9.

Constraints are of two types: (i)  $B1 = 9, \ldots, H9 = 9$  and (ii) AllDiff(A1,...,A9), AllDiff(A1,...,I1), AllDiff(A1,...,C3), ...

Can we fill in the blanks with digits  $1, 2, \ldots, 9$  so that no digit appears twice in any row, column or  $3 \times 3$  box?



Variables: A1, A2, ..., I9 (81 in total). Values: 1, 2, 3, 4, 5, 6, 7, 8, 9. Constraints are of two types: (i) B1 = 9, ..., H9 = 9 and (ii) AllDiff(A1,..., A9), AllDiff(A1,..., I1), AllDiff(A1,..., C3), ...

Can we fill in the blanks with digits  $1, 2, \ldots, 9$  so that no digit appears twice in any row, column or  $3 \times 3$  box?

	1	2	3	4	5	6	7	8	9
Α	4	8	3	9	2	1	6	5	7
в	9	6	7	3	4	5	8	2	1
С	2	5	1	8	7	6	4	9	3
D	5	4	8	1	3	2	9	7	6
Е	7	2	9	5	6	4	1	3	8
F	1	3	6	7	9	8	2	4	5
G	3	7	2	6	8	9	5	1	4
н	8	1	4	2	5	3	7	6	9
Т	6	9	5	4	1	7	3	8	2

Variables: A1, A2, ..., I9 (81 in total). Values: 1, 2, 3, 4, 5, 6, 7, 8, 9. Constraints are of two types: (i) B1 = 9, ..., H9 = 9 and (ii) AllDiff(A1,..., A9), AllDiff(A1,..., I1), AllDiff(A1,..., C3), ... • Brute force: try all  $|D|^{|V|}$  assignments (applicable only if |D| is finite).

3 1 3

- Brute force: try all  $|D|^{|V|}$  assignments (applicable only if |D| is finite).
- Can we do better than that?

- Brute force: try all  $|D|^{|V|}$  assignments (applicable only if |D| is finite).
- Can we do better than that?
- LINEAR EQUATIONS OVER  $\mathbb{F}_2$ :

- Brute force: try all  $|D|^{|V|}$  assignments (applicable only if |D| is finite).
- Can we do better than that?
- LINEAR EQUATIONS OVER  $\mathbb{F}_2$ : yes! Gaussian elimination.

- Brute force: try all  $|D|^{|V|}$  assignments (applicable only if |D| is finite).
- Can we do better than that?
- LINEAR EQUATIONS OVER  $\mathbb{F}_2$ : yes! Gaussian elimination.
- 2-Coloring:

- Brute force: try all  $|D|^{|V|}$  assignments (applicable only if |D| is finite).
- Can we do better than that?
- LINEAR EQUATIONS OVER  $\mathbb{F}_2$ : yes! Gaussian elimination.
- 2-COLORING: yes! Use constraint propagation (next slide).

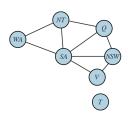
- Brute force: try all  $|D|^{|V|}$  assignments (applicable only if |D| is finite).
- Can we do better than that?
- LINEAR EQUATIONS OVER  $\mathbb{F}_2$ : yes! Gaussian elimination.
- 2-COLORING: yes! Use constraint propagation (next slide).
- 3-Coloring:

- Brute force: try all  $|D|^{|V|}$  assignments (applicable only if |D| is finite).
- Can we do better than that?
- LINEAR EQUATIONS OVER  $\mathbb{F}_2$ : yes! Gaussian elimination.
- 2-COLORING: yes! Use constraint propagation (next slide).
- 3-COLORING: probably not.

- Brute force: try all  $|D|^{|V|}$  assignments (applicable only if |D| is finite).
- Can we do better than that?
- LINEAR EQUATIONS OVER  $\mathbb{F}_2$ : yes! Gaussian elimination.
- 2-COLORING: yes! Use constraint propagation (next slide).
- 3-COLORING: probably not.
- CSP in general:

- Brute force: try all  $|D|^{|V|}$  assignments (applicable only if |D| is finite).
- Can we do better than that?
- LINEAR EQUATIONS OVER  $\mathbb{F}_2$ : yes! Gaussian elimination.
- 2-COLORING: yes! Use constraint propagation (next slide).
- 3-COLORING: probably not.
- CSP in general: probably not.

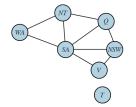
- Brute force: try all  $|D|^{|V|}$  assignments (applicable only if |D| is finite).
- Can we do better than that?
- LINEAR EQUATIONS OVER  $\mathbb{F}_2$ : yes! Gaussian elimination.
- 2-COLORING: yes! Use constraint propagation (next slide).
- 3-COLORING: probably not.
- CSP in general: probably not.
- probably stands for "unless P=NP" (more on that later).



#### 1. Keep record of values for each pair.

- 2. Consider all triple of variables.
- 3. Remove 2-incosistent assignments.

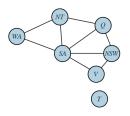
- 1. Keep record of values for each pair.
- 2. Consider all triple of variables.



3. Remove 2-incosistent assignments.

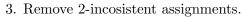
- 1. Keep record of values for each pair.
- 2. Consider all triple of variables.

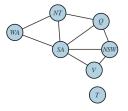
3. Remove 2-incosistent assignments.



WA	SA	V
0	0	0
0	0	1
0	1	0
0	1	1
1	0	0
1	0	1
1	1	0
1	1	1

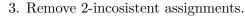
- 1. Keep record of values for each pair.
- 2. Consider all triple of variables.



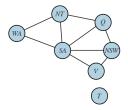


WA	SA	V
0	0	0
0	0	1
0	1	0
0	1	1
1	0	0
1	0	1
1	1	0
1	1	1

- 1. Keep record of values for each pair.
- 2. Consider all triple of variables.



WA	SA	V
0	0	0
		1
0	1	0
	1	1
1		
1	0	1
1	1	0
1	1	1

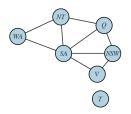


- 1. Keep record of values for each pair.
- 2. Consider all triple of variables.

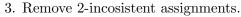
3. Remove 2-incosistent assignments.

WA	SA	NT
0	1	0
0	1	1
1	0	0
1	0	1

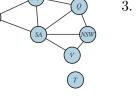




- 1. Keep record of values for each pair.
- 2. Consider all triple of variables.

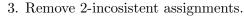


WA	SA	NT
0	1	0
0	1	1
1	0	0
1	0	1

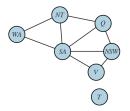


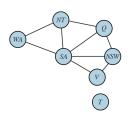
WA

- 1. Keep record of values for each pair.
- 2. Consider all triple of variables.



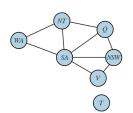
WA	SA	NT
0	1	0
	1	1
1		
1		1





- 1. Keep record of values for each pair.
- 2. Consider all triple of variables.
- 3. Remove 2-incosistent assignments.
- 4. If no record changed, stop.

5. Else, go to step 2.



- 1. Keep record of values for each pair.
- 2. Consider all triple of variables.
- 3. Remove 2-incosistent assignments.
- 4. If no record changed, stop.
- 5. Else, go to step 2.

- 1. Keep record of values for each pair.
- 2. Consider all triple of variables.
- 3. Remove 2-incosistent assignments.
- 4. If no record changed, stop.
- 5. Else, go to step 2.

• If some record is empty, inconsistency has been detected.

- 1. Keep record of values for each pair.
- 2. Consider all triple of variables.
- 3. Remove 2-incosistent assignments.
- 4. If no record changed, stop.
- 5. Else, go to step 2.

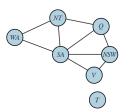
• If some record is empty, inconsistency has been detected.

• For 2-COLORING, (2,3)-consistency test is sufficient.

Solving 2-COLORING with (2,3)-consistency algorithm.

- 1. Keep record of values for each pair.
- 2. Consider all triple of variables.
- 3. Remove 2-incosistent assignments.
- 4. If no record changed, stop.
- 5. Else, go to step 2.

- If some record is empty, inconsistency has been detected.
- For 2-COLORING, (2,3)-consistency test is sufficient.
- Running time:  $O(|V|^3)$ .



## • Which CSPs are locally consistent?

- Restrict the set of values and the set of possible constraints.
- $CSP(\{0,1\};\neq)$  is (2,3)-consistent.
- $\operatorname{CSP}(\{0,1\}; x \oplus y \oplus z = 0, x \oplus y \oplus z = 1)$  is not  $(\ell, k)$ -consistent for any fixed  $\ell, k$ .

#### Theorem (Feder, Vardi '98)

- Which CSPs are locally consistent?
- Restrict the set of values and the set of possible constraints.
- $CSP(\{0,1\};\neq)$  is (2,3)-consistent.
- $\operatorname{CSP}(\{0,1\}; x \oplus y \oplus z = 0, x \oplus y \oplus z = 1)$  is not  $(\ell, k)$ -consistent for any fixed  $\ell, k$ .

- Which CSPs are locally consistent?
- Restrict the set of values and the set of possible constraints.
- $CSP(\{0,1\};\neq)$  is (2,3)-consistent.
- $\operatorname{CSP}(\{0,1\}; x \oplus y \oplus z = 0, x \oplus y \oplus z = 1)$  is not  $(\ell, k)$ -consistent for any fixed  $\ell, k$ .

- Which CSPs are locally consistent?
- Restrict the set of values and the set of possible constraints.
- $CSP(\{0,1\};\neq)$  is (2,3)-consistent.
- $\operatorname{CSP}(\{0,1\}; x \oplus y \oplus z = 0, x \oplus y \oplus z = 1)$  is not  $(\ell, k)$ -consistent for any fixed  $\ell, k$ .

- Which CSPs are locally consistent?
- Restrict the set of values and the set of possible constraints.
- $CSP(\{0,1\};\neq)$  is (2,3)-consistent.
- $\operatorname{CSP}(\{0,1\}; x \oplus y \oplus z = 0, x \oplus y \oplus z = 1)$  is not  $(\ell, k)$ -consistent for any fixed  $\ell, k$ .

- $(\ell, k)$ -consistent CSPs are solvable in  $O(|V|^k)$  time.
- Gaussian elimination runs in  $O(|C|^3)$  time.
- Which CSPs are solvable in polynomial time?
- Don't know how to answer such questions unconditionally.
- Instead, assume  $P \neq NP$ , and prove NP-completeness.

- $\blacksquare$   $(\ell,k)\text{-consistent CSPs}$  are solvable in  $O(|V|^k)$  time.
- Gaussian elimination runs in  $O(|C|^3)$  time.
- Which CSPs are solvable in polynomial time?
- Don't know how to answer such questions unconditionally.
- Instead, assume  $P \neq NP$ , and prove NP-completeness.

- $(\ell, k)$ -consistent CSPs are solvable in  $O(|V|^k)$  time.
- Gaussian elimination runs in  $O(|C|^3)$  time.
- Which CSPs are solvable in polynomial time?
- Don't know how to answer such questions unconditionally.
- Instead, assume  $P \neq NP$ , and prove NP-completeness.

- $(\ell, k)$ -consistent CSPs are solvable in  $O(|V|^k)$  time.
- Gaussian elimination runs in  $O(|C|^3)$  time.
- Which CSPs are solvable in polynomial time?
- Don't know how to answer such questions unconditionally.
- Instead, assume  $P \neq NP$ , and prove NP-completeness.

- $(\ell, k)$ -consistent CSPs are solvable in  $O(|V|^k)$  time.
- Gaussian elimination runs in  $O(|C|^3)$  time.
- Which CSPs are solvable in polynomial time?
- Don't know how to answer such questions unconditionally.
- Instead, assume  $P \neq NP$ , and prove NP-completeness.

- in P if finding a solution takes polynomial time.
- in NP if verifying a solution takes polynomial time.

- $\blacksquare$  P  $\subseteq$  NP. Whether the inclusion is strict is unknown.
- NP-complete problems are "the most difficult" in NP. Solving one in polynomial time means P=NP.
- Hence, if P≠NP, then NP-complete problems are not solvable in polynomial time.

- in P if finding a solution takes polynomial time.
- in NP if verifying a solution takes polynomial time.

- $\blacksquare$  P  $\subseteq$  NP. Whether the inclusion is strict is unknown.
- NP-complete problems are "the most difficult" in NP. Solving one in polynomial time means P=NP.
- Hence, if P≠NP, then NP-complete problems are not solvable in polynomial time.

- in P if finding a solution takes polynomial time.
- in NP if verifying a solution takes polynomial time.

- $\blacksquare$  P  $\subseteq$  NP. Whether the inclusion is strict is unknown.
- NP-complete problems are "the most difficult" in NP. Solving one in polynomial time means P=NP.
- Hence, if P≠NP, then NP-complete problems are not solvable in polynomial time.

- in P if finding a solution takes polynomial time.
- in NP if verifying a solution takes polynomial time.

- $\blacksquare$  P  $\subseteq$  NP. Whether the inclusion is strict is unknown.
- NP-complete problems are "the most difficult" in NP.
   Solving one in polynomial time means P=NP.
- Hence, if P≠NP, then NP-complete problems are not solvable in polynomial time.

- in P if finding a solution takes polynomial time.
- in NP if verifying a solution takes polynomial time.

- $\blacksquare$  P  $\subseteq$  NP. Whether the inclusion is strict is unknown.
- NP-complete problems are "the most difficult" in NP.
   Solving one in polynomial time means P=NP.
- Hence, if P≠NP, then NP-complete problems are not solvable in polynomial time.

- in P if finding a solution takes polynomial time.
- in NP if verifying a solution takes polynomial time.

- $P \subseteq NP$ . Whether the inclusion is strict is unknown.
- NP-complete problems are "the most difficult" in NP.
   Solving one in polynomial time means P=NP.
- Hence, if P≠NP, then NP-complete problems are not solvable in polynomial time.

- Which CSPs are solvable in polynomial time?
- Don't know how to answer such questions unconditionally.
- Instead, assume  $P \neq NP$ , and prove NP-completeness.
- $\operatorname{CSP}(\{0,1\};\neq)$  is in P.
- $\blacksquare CSP(\{0,1\}; x \oplus y \oplus z = 0, x \oplus y \oplus z = 1) \text{ is in P.}$
- $CSP(\{0,1\}; x + y + z = 1)$  is NP-complete.
- $CSP(\{0, 1, 2\}; \neq)$  is NP-complete.

#### Conjecture (Feder, Vardi '98)

- Which CSPs are solvable in polynomial time?
- Don't know how to answer such questions unconditionally.
- $\blacksquare$  Instead, assume P $\neq$ NP, and prove NP-completeness.
- $\operatorname{CSP}(\{0,1\};\neq)$  is in P.
- $\blacksquare CSP(\{0,1\}; x \oplus y \oplus z = 0, x \oplus y \oplus z = 1) \text{ is in P.}$
- $CSP(\{0,1\}; x + y + z = 1)$  is NP-complete.
- $CSP(\{0, 1, 2\}; \neq)$  is NP-complete.

#### Conjecture (Feder, Vardi '98)

- Which CSPs are solvable in polynomial time?
- Don't know how to answer such questions unconditionally.
- Instead, assume  $P \neq NP$ , and prove NP-completeness.
- $\operatorname{CSP}(\{0,1\};\neq)$  is in P.
- $\operatorname{CSP}(\{0,1\}; x \oplus y \oplus z = 0, x \oplus y \oplus z = 1)$  is in P.
- $CSP(\{0, 1\}; x + y + z = 1)$  is NP-complete.
- $CSP(\{0, 1, 2\}; \neq)$  is NP-complete.

#### Conjecture (Feder, Vardi '98)

- Which CSPs are solvable in polynomial time?
- Don't know how to answer such questions unconditionally.
- Instead, assume  $P \neq NP$ , and prove NP-completeness.
- $\operatorname{CSP}(\{0,1\};\neq)$  is in P.
- $\operatorname{CSP}(\{0,1\}; x \oplus y \oplus z = 0, x \oplus y \oplus z = 1)$  is in P.
- $\operatorname{CSP}(\{0,1\}; x + y + z = 1)$  is NP-complete.
- $CSP(\{0, 1, 2\}; \neq)$  is NP-complete.

#### Conjecture (Feder, Vardi '98)

- Which CSPs are solvable in polynomial time?
- Don't know how to answer such questions unconditionally.
- Instead, assume  $P \neq NP$ , and prove NP-completeness.
- $\operatorname{CSP}(\{0,1\};\neq)$  is in P.
- $\operatorname{CSP}(\{0,1\}; x \oplus y \oplus z = 0, x \oplus y \oplus z = 1)$  is in P.
- $\operatorname{CSP}(\{0,1\}; x + y + z = 1)$  is NP-complete.
- $\blacksquare$  CSP({0, 1, 2}; \neq) is NP-complete.

#### Conjecture (Feder, Vardi '98)

- Which CSPs are solvable in polynomial time?
- Don't know how to answer such questions unconditionally.
- Instead, assume  $P \neq NP$ , and prove NP-completeness.
- $\operatorname{CSP}(\{0,1\};\neq)$  is in P.
- $\operatorname{CSP}(\{0,1\}; x \oplus y \oplus z = 0, x \oplus y \oplus z = 1)$  is in P.
- $\operatorname{CSP}(\{0,1\}; x + y + z = 1)$  is NP-complete.
- $CSP(\{0, 1, 2\}; \neq)$  is NP-complete.

Any CSP with finite domain is either in P or NP-complete.

## $\blacksquare$ If P $\subsetneq$ NP, there are many artificial problems in between.

- In this sense, CSP is a natural computational problem.
- Proved in 2017 by Bulatov and Zhuk (independently).
- Both proofs use *universal algebra*.
- Intuitively, CSP is in P if allowed constraints share "symmetries", and NP-complete otherwise.

- $\blacksquare$  If P $\subsetneq$ NP, there are many artificial problems in between.
- In this sense, CSP is a natural computational problem.
- Proved in 2017 by Bulatov and Zhuk (independently).
- Both proofs use *universal algebra*.
- Intuitively, CSP is in P if allowed constraints share "symmetries", and NP-complete otherwise.

- $\blacksquare$  If P $\subsetneq$ NP, there are many artificial problems in between.
- In this sense, CSP is a natural computational problem.
- Proved in 2017 by Bulatov and Zhuk (independently).
- Both proofs use *universal algebra*.
- Intuitively, CSP is in P if allowed constraints share "symmetries", and NP-complete otherwise.

### Theorem (Bulatov, Zhuk, '17)

- $\blacksquare$  If P $\subsetneq$ NP, there are many artificial problems in between.
- In this sense, CSP is a natural computational problem.
- Proved in 2017 by Bulatov and Zhuk (independently).
- Both proofs use *universal algebra*.
- Intuitively, CSP is in P if allowed constraints share "symmetries", and NP-complete otherwise.

#### Theorem (Bulatov, Zhuk, '17)

- $\blacksquare$  If P $\subsetneq$ NP, there are many artificial problems in between.
- In this sense, CSP is a natural computational problem.
- Proved in 2017 by Bulatov and Zhuk (independently).
- Both proofs use *universal algebra*.
- Intuitively, CSP is in P if allowed constraints share "symmetries", and NP-complete otherwise.

## ■ Many interesting CSPs are NP-complete. What to do?

- A problem is in P if we can find an exact solution for any instance in polynomial time.
- We have to give up something
  - ▷ Look for approximate solutions (MAXCSP).
  - ▷ Use heuristics (like local consistency)
  - ▷ Design parameterized algorithms.
  - > Design moderately super-polynomial algorithms.

- Many interesting CSPs are NP-complete. What to do?
- A problem is in P if we can find an exact solution for any instance in polynomial time.
- We have to give up something
  - ▷ Look for approximate solutions (MAXCSP).
  - ▷ Use heuristics (like local consistency)
  - ▷ Design parameterized algorithms.
  - > Design moderately super-polynomial algorithms.

- Many interesting CSPs are NP-complete. What to do?
- A problem is in P if we can find an exact solution for any instance in polynomial time.
- We have to give up something
  - $\triangleright$  Look for approximate solutions (MAXCSP).
  - ▷ Use heuristics (like local consistency)
  - ▷ Design parameterized algorithms.
  - ▷ Design moderately super-polynomial algorithms.

- Many interesting CSPs are NP-complete. What to do?
- A problem is in P if we can find an exact solution for any instance in polynomial time.
- We have to give up something
  - $\triangleright$  Look for approximate solutions (MAXCSP).
  - ▷ Use heuristics (like local consistency)
  - ▷ Design parameterized algorithms.
  - ▷ Design moderately super-polynomial algorithms.

- Many interesting CSPs are NP-complete. What to do?
- A problem is in P if we can find an exact solution for any instance in polynomial time.
- We have to give up something
  - ▷ Look for approximate solutions (MAXCSP).
  - ▷ Use heuristics (like local consistency)
  - ▷ Design parameterized algorithms.
  - ▷ Design moderately super-polynomial algorithms.

- Many interesting CSPs are NP-complete. What to do?
- A problem is in P if we can find an exact solution for any instance in polynomial time.
- We have to give up something
  - ▷ Look for approximate solutions (MAXCSP).
  - ▷ Use heuristics (like local consistency)
  - $\triangleright~$  Design parameterized algorithms.
  - ▷ Design moderately super-polynomial algorithms.

- Many interesting CSPs are NP-complete. What to do?
- A problem is in P if we can find an exact solution for any instance in polynomial time.
- We have to give up something
  - ▷ Look for approximate solutions (MAXCSP).
  - ▷ Use heuristics (like local consistency)
  - $\triangleright~$  Design parameterized algorithms.
  - $\triangleright~$  Design moderately super-polynomial algorithms.

## • What about CSPs with infinite domains?

- Many interesting problems:
  - ▷ CSP(Q; <) aka DIGRAPH ACYCLICITY.
  - ▷ CSP(Q; <, =, >) aka Point Algebra.
  - ▷  $CSP(\mathbb{Q}; x y \le a \mid a \in \mathbb{Q})$  aka Simple Temporal Problem.
  - $\triangleright$  CSP(Q; linear inequalities).
  - $\triangleright$  CSP( $\mathbb{Z}$ ; linear inequalities).
- There is no dichotomy for infinite-domain CSPs.

## • What about CSPs with infinite domains?

### Many interesting problems:

- ▷  $\operatorname{CSP}(\mathbb{Q}; <)$  aka Digraph Acyclicity.
- ▷  $CSP(\mathbb{Q}; <, =, >)$  aka Point Algebra.
- ▷  $CSP(\mathbb{Q}; x y \le a \mid a \in \mathbb{Q})$  aka Simple Temporal Problem.
- $\triangleright$  CSP( $\mathbb{Q}$ ; linear inequalities).
- $\triangleright$  CSP( $\mathbb{Z}$ ; linear inequalities).
- There is no dichotomy for infinite-domain CSPs.

- What about CSPs with infinite domains?
- Many interesting problems:
  - $\triangleright~\mathrm{CSP}(\mathbb{Q};<)$ aka Digraph Acyclicity.
  - ▷  $CSP(\mathbb{Q}; <, =, >)$  aka Point Algebra.
  - ▷  $\operatorname{CSP}(\mathbb{Q}; x y \leq a \mid a \in \mathbb{Q})$  aka Simple Temporal Problem.
  - $\triangleright$  CSP( $\mathbb{Q}$ ; linear inequalities).
  - $\triangleright$  CSP( $\mathbb{Z}$ ; linear inequalities).
- There is no dichotomy for infinite-domain CSPs.

- What about CSPs with infinite domains?
- Many interesting problems:
  - ▷  $CSP(\mathbb{Q}; <)$  aka Digraph Acyclicity.
  - ▷  $CSP(\mathbb{Q}; <, =, >)$  aka Point Algebra.
  - ▷  $\operatorname{CSP}(\mathbb{Q}; x y \leq a \mid a \in \mathbb{Q})$  aka Simple Temporal Problem.
  - $\triangleright$  CSP( $\mathbb{Q}$ ; linear inequalities).
  - $\triangleright$  CSP( $\mathbb{Z}$ ; linear inequalities).
- There is no dichotomy for infinite-domain CSPs.

- What about CSPs with infinite domains?
- Many interesting problems:
  - ▷  $CSP(\mathbb{Q}; <)$  aka Digraph Acyclicity.
  - $\triangleright \ \operatorname{CSP}(\mathbb{Q};<,=,>)$ aka Point Algebra.
  - ▷  $CSP(\mathbb{Q}; x y \le a \mid a \in \mathbb{Q})$  aka Simple Temporal Problem.
  - $\triangleright$  CSP(Q; linear inequalities).
  - $\triangleright$  CSP( $\mathbb{Z}$ ; linear inequalities).
- There is no dichotomy for infinite-domain CSPs.

- What about CSPs with infinite domains?
- Many interesting problems:
  - ▷  $CSP(\mathbb{Q}; <)$  aka Digraph Acyclicity.
  - $\triangleright \ \operatorname{CSP}(\mathbb{Q};<,=,>)$ aka Point Algebra.
  - ▷  $CSP(\mathbb{Q}; x y \le a \mid a \in \mathbb{Q})$  aka Simple Temporal Problem.
  - $\triangleright$  CSP( $\mathbb{Q}$ ; linear inequalities).
  - $\triangleright$  CSP( $\mathbb{Z}$ ; linear inequalities).
- There is no dichotomy for infinite-domain CSPs.

- What about CSPs with infinite domains?
- Many interesting problems:
  - ▷  $CSP(\mathbb{Q}; <)$  aka Digraph Acyclicity.
  - ▷  $CSP(\mathbb{Q}; <, =, >)$  aka Point Algebra.
  - ▷  $CSP(\mathbb{Q}; x y \le a \mid a \in \mathbb{Q})$  aka Simple Temporal Problem.
  - $\triangleright$  CSP( $\mathbb{Q}$ ; linear inequalities).
  - $\triangleright$  CSP( $\mathbb{Z}$ ; linear inequalities).
- There is no dichotomy for infinite-domain CSPs.

- What about CSPs with infinite domains?
- Many interesting problems:
  - ▷  $CSP(\mathbb{Q}; <)$  aka Digraph Acyclicity.
  - ▷  $CSP(\mathbb{Q}; <, =, >)$  aka Point Algebra.
  - ▷  $CSP(\mathbb{Q}; x y \le a \mid a \in \mathbb{Q})$  aka Simple Temporal Problem.
  - $\triangleright$  CSP( $\mathbb{Q}$ ; linear inequalities).
  - $\triangleright$  CSP( $\mathbb{Z}$ ; linear inequalities).
- There is no dichotomy for infinite-domain CSPs.

# Thank You!

표 표